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# **NOAA UAS Program Office Capabilities and GOES-R Support**

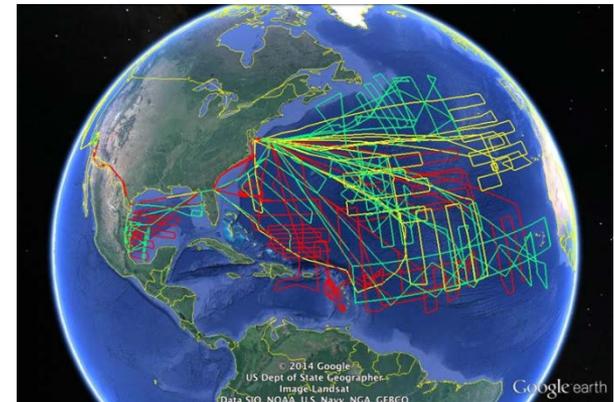
**NOAA UAS Program  
April 2015**



# NOAA UAS Program Vision and Key Roles



- ***Vision***
  - UAS observations will become an essential component of the NOAA observing system
- ***Key Roles***
  - Serve as the NOAA subject matter experts for UAS technology and observations
  - Assist with the research, development, demonstration and transition to application of select UAS observing strategies
- ***Science Focus Areas***
  - High Impact Weather Observations
  - Polar Observations
  - Marine Observations





# Fixed-Wing UAS Capabilities



## High Altitude Long Endurance (HALE)

- Maximum Altitude 65,000 ft
- Maximum Endurance 25 hrs
- Maximum Payload Weight 1200 lbs



## Medium Altitude Long Endurance (MALE)

- Maximum Altitude 40000 ft
- Maximum Endurance 24 hrs
- Maximum Payload Weight 400 lbs int, 2000 lbs ext



## Low Altitude Long Endurance (LALE)

- Maximum Altitude 19,500 ft
- Maximum Endurance 24 hrs
- Maximum Payload Weight 13.5 lbs



## Low Altitude Short Endurance (LASE)

- Maximum Altitude 1000 ft (operating altitude, higher capable)
- Maximum Endurance 2 hrs
- Maximum Payload Weight approx 2 lbs



# Other Unmanned Capabilities



## Vertical Takeoff and Landing (VTOL)

- Maximum Altitude 3280 ft
- Maximum Endurance 1.4 hr
- Maximum Payload Weight 1.7 lb



## Aircraft-launched UAS (ACL)

- Maximum Altitude 20,000 ft
- Maximum Endurance 1.5 hrs
- Maximum Payload Weight 0.9 lbs



## Balloon-launched UAS (BL)

- Maximum Altitude 100,000 ft
- Maximum Endurance N/A
- Maximum Payload Weight 3 lbs



## Surface Unmanned Vehicles (SUV)

- Maximum Altitude Sea Level
- Maximum Endurance 8.6 hr
- Maximum Payload Weight 15 lb



## Tethered Balloons (TB)

- Maximum Altitude 25,000 ft
- Maximum Endurance N/A
- Maximum Payload Weight 2,200 lbs



# NOAA GOES-R Advanced Baseline Imager Calibration and Validation UAS Mission Overview



## GOES-R ABI Cal/Val Mission Needs:

- ▶ Operations over three types of environments:
  - 1) Ocean (100 km offshore)
  - 2) Land – Vegetated
  - 3) Land – Barren Desert
  
- ▶ Sensor packages to obtain radiation data...
  - UV-Vis-NIR Spectrum Radiation (0.2 – 1.1 $\mu$ m)
  - LWIR Spectrum (~10.0 – 12.5 $\mu$ m)
  - SWIR Spectrum (1.6 – 2.25 $\mu$ m) [Potential]
  
- ▶ Coordinate UAS missions with simultaneous ER-2 flyover observations and geostationary satellite-based observations
  
- ▶ Nadir and Off-nadir autonomous observations, depending upon sub-mission requirements





# NOAA GOES-R Advanced Baseline Imager Calibration and Validation UAS Mission Overview



## Requirements Review: Oceanic Cal/Val Component

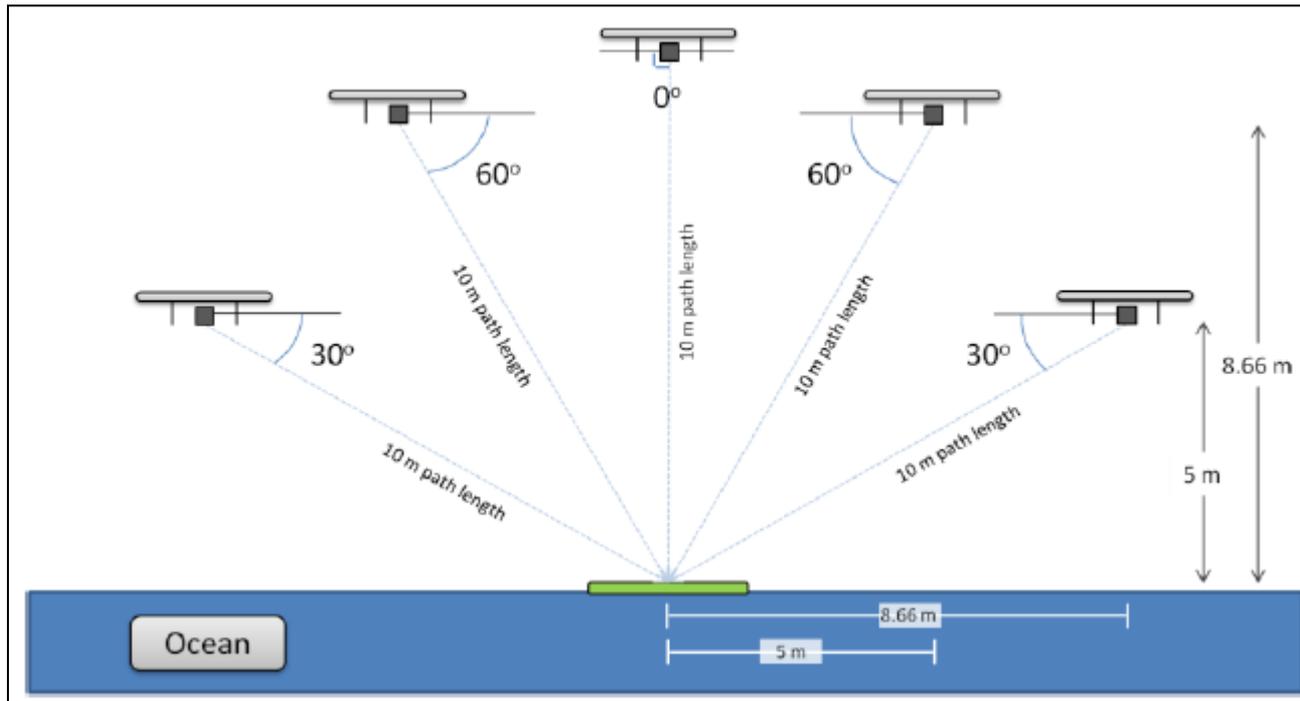
- ▶ Request for VTOL (i.e. “rotary wing”) UAS platform operations
- ▶ Autonomously control the view geometry of the sensor payloads for oblique angle data collection of a fixed earth target
- ▶ View geometry:
  - Nadir to  $\geq 70$  degrees off-nadir (ideally approaching 90 degrees)
  - Maintain a 10 m (no more than 15 m) distance from target
- ▶ Payload Types/Data:
  - 1) Spectrometer (UV-VIS-NIR spectral range)
  - 2) Radiometer (LWIR spectral range)
- ▶ Metadata will be collected and stored:
  - Image acquisition times, sensor geometry angles, GPS location



## Proposed CONOPS Review: Oceanic Cal/Val Component

### ► Definition: Single Pass from One Target Collection

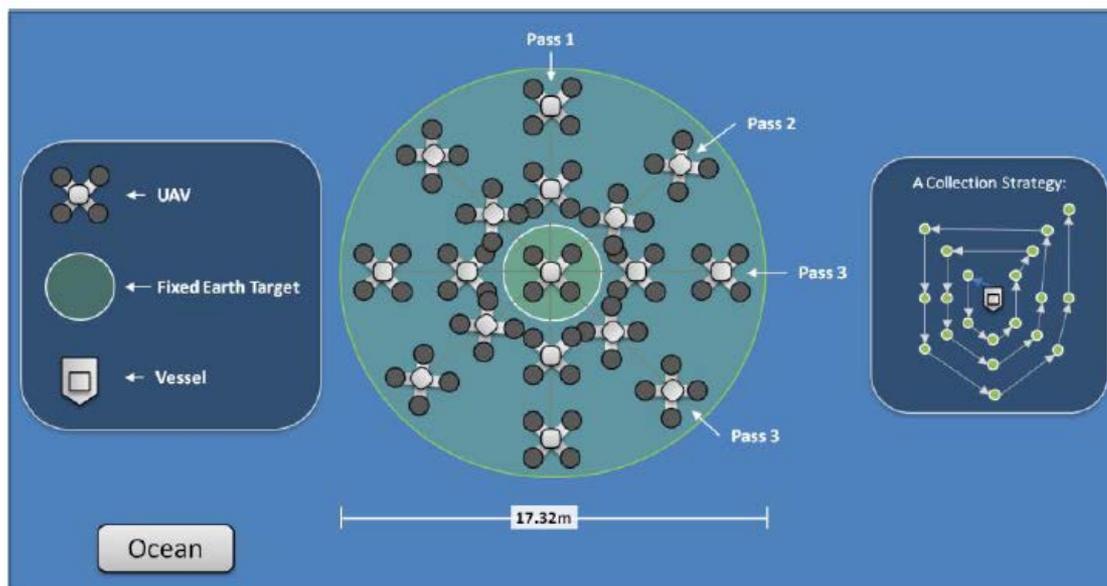
- Maintain a fixed radius of 10 meters, ideally (no more than 15 meters)
- Start at a large off-nadir angle (70 to 90 degrees), then fly VTOL UAS on an arc up and over a fixed ocean target, ending the pass at the same off-nadir angle on the other side
- Sensors remain fixed on the target during the entire overpass.



## Proposed CONOPS Review: Oceanic Cal/Val Component

### ► Definition: Complete Collection for One Target

- Repeat for a total of four passes, rotating azimuthally around a target, essentially piecing together a collection of target observations from as many different observation angles within the skyward hemisphere as possible.



### ► Definition: Full Mission Collection

- Repeat target observation collections for multiple targets, radiating outward from a central location (likely a ship) until a sizeable enough footprint of the ocean surface has been sampled (initially proposed to be ~1 to 5 km out in all directions.)

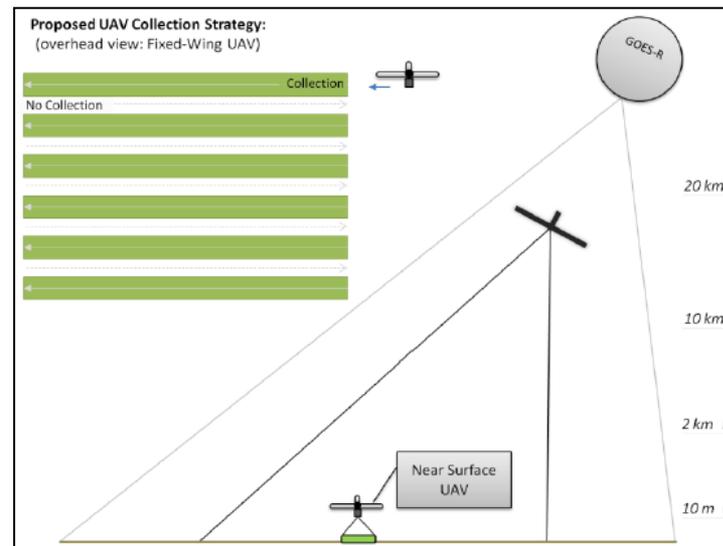
## Requirements Review: Land Cal/Val Component

- ▶ Request for small fixed wing UAS platform operations
- ▶ View geometry:
  - Nadir view
  - Maintain a 10 m (no more than 20 m) distance from surface
- ▶ Payload Types/Data:
  - Radiometer (LWIR spectral range)



## Proposed CONOPS Review: Land Cal/Val Component

- ▶ Obtain surface brightness temperature data of vegetated and barren desert land surfaces
- ▶ Use fixed wing UAS platform with nadir-looking sensors to cover a broad geographic region (~5 to 20 km)
- ▶ Autonomous flight through pre-flight programming of waypoints
- ▶ “Lawn-mower Pattern” flight paths used to fully canvas the footprint within the GOES-R satellite ABI infrared band pixels
- ▶ Metadata will be collected and stored:
  - ▶ Image acquisition times, sensor geometry angles, GPS location





# NOAA GOES-R Advanced Baseline Imager Calibration and Validation UAS Mission Overview



## Sensor Payload Recommendations and Synopsis:

### ▶ *LWIR Sensor: “Apogee / SI-series”*

The Apogee S1-series of sensors provides the highest amount of accuracy (least error), which is balanced against a reasonable response time. It also provides for one of the smaller and lighter payload solutions. Furthermore, this line of instruments has a history of use aboard UAS platforms for crop monitoring missions and has also been mounted to the front of ships for sea surface temperature measurements.

### ▶ *UV-VIS-NIR Sensor: “StellarNet / BLK-C-SR” (with PDA detector option)*

The StellarNet Black Comet Super Resolution (BLK-C-SR) sensor with the Toshiba TCD1201D photodiode array detector configuration boasts the highest signal-to-noise ratio while maintaining an optical resolution that is right on par with other comparable sensors. At a weight of 0.40 kg, which puts it in the middle of the pack with respect to this specification, the benefits appear to far outweigh this minor drawback.

### ▶ *NIR-SWIR Sensor: “Ocean Optics / NIRQuest512-2.5”*

The Ocean Optics NIRQuest512-2.5 possesses the largest amount of weight in this class of researched sensors; however, this instrument provides a relatively high optical resolution while yielding a signal-to-noise ratio that is a full one to two orders of magnitude greater than other comparable sensors.

# **Backup Slides**

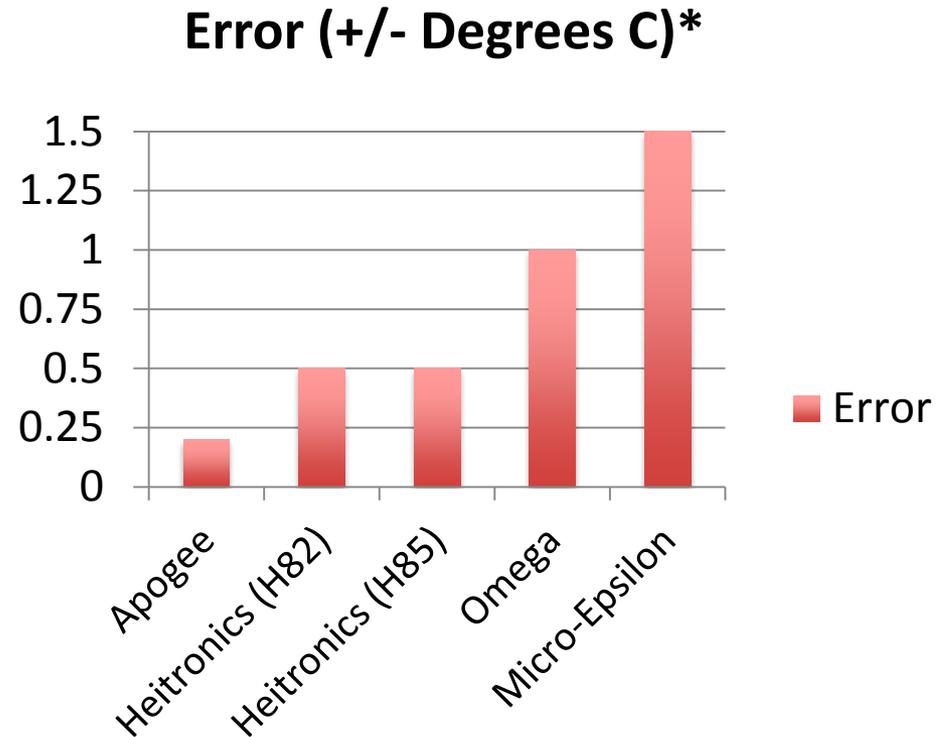
# Long-wave IR (LWIR) / 8.0-14.0 $\mu\text{m}$ Range Spectral Sensor Specifications

Manufacturer	Heitronics	Heitronics	Apogee	Micro-Epsilon	Omega
Sensor Model	"KT15.85 IIP"*	"KT15.82 IIP"	"SI" Series	"ThermoMETER CS"	"OS301-LT"
Spectral Range ( $\mu\text{m}$ )	9.6 – 11.5	8.0 – 14.0	8.0 – 14.0	8.0 – 14.0	8.0 – 14.0
Calibrated Targeted Temperature Range	-25 – 200 C	-30 – 1,000 C	-30 – 65 C	-40 – 400 C	-20 – 100 C
Temperature Accuracy	0.5 C, Plus 0.7% diff b/w target and housing temp	0.5 C, Plus 0.7% diff b/w target and housing temp	0.2 C	1.5 C, Or +/- 1.5 %	1.0 C, Or +/- 1.0 %
Temperature Resolution	0.40 C**	0.05 C**	Dependent upon data logger ***	0.10 C ****	Dependent upon data logger ***
Response Time	1.00 s	1.00 s	0.60 s (95% response)	0.03 s (90% response)	0.24 s (90% response)
Sensor Weight	1.300 kg	1.300 kg	0.190 kg	0.058 kg	0.095 kg
Payload Dimensions (cm)	L x W x H: 16.1 x 5.1 x 5.1	L x W x H: 16.1 x 5.1 x 5.1	Diameter x L: 2.3 x 6.0	Diameter x L: 1.4 x 8.7	Diameter x L: 1.8 x 10.3
Operational Environment Temperatures	-20 – 60 C	-20 – 60 C	-55 – 80 C	-20 – 80 C	0 – 70 C
Operational Environment Humidity	<i>(Not Provided)</i>	<i>(Not Provided)</i>	0 to 100%, Non-condensing	10 to 95%, Non-condensing	0 to 95%, Non-condensing
Power	Direct: 22.0 – 30.0 V Alternating: ~24.0 V	Direct: 22.0 – 30.0 V Alternating: ~24.0 V	2.5 V	Direct: 5.0 – 30.0 V	Direct: 24.0 – 28.0 V

- \* Advertised for "meteorological" remote sensing applications
- \*\* Dependent on target temperature and response time / Shown, with Detector Type "A" @ 20C Target Temp
- \*\*\* Potentially 0.05 C sensitivity with data logger resolution of 3  $\mu\text{V}$ .
- \*\*\*\* Target temp <100°C and time constant >0.2s.

## Long-wave Spectral Sensors: Temperature Accuracy Comparison

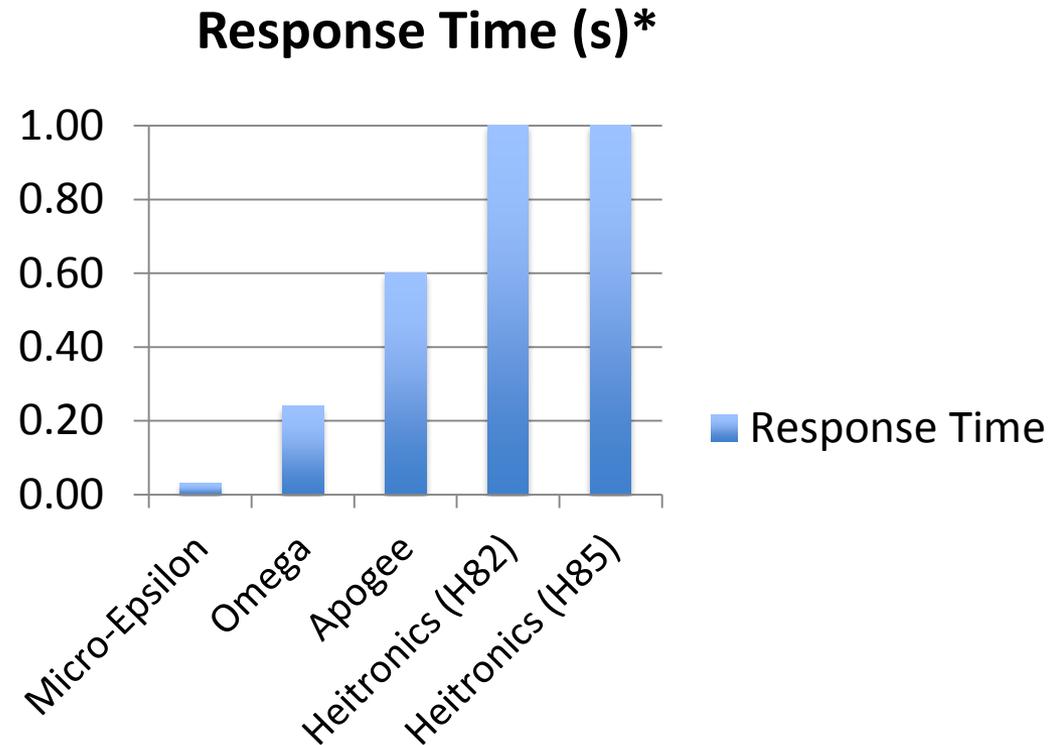
Rank	Sensor	Error (+/-)
1	Apogee "SI" Series	0.2 C
2a	Heitronics "KT15.82" (H82)	0.5 C
2b	Heitronics "KT15.85" (H85)	0.5 C
3	Omega "OS301-LT"	1.0 C
4	Micro-Epsilon "ThermoMETER CS"	1.5 C



*\*Lower values indicate improved performance attributes*

# Long-wave Spectral Sensors: Response Time Comparison

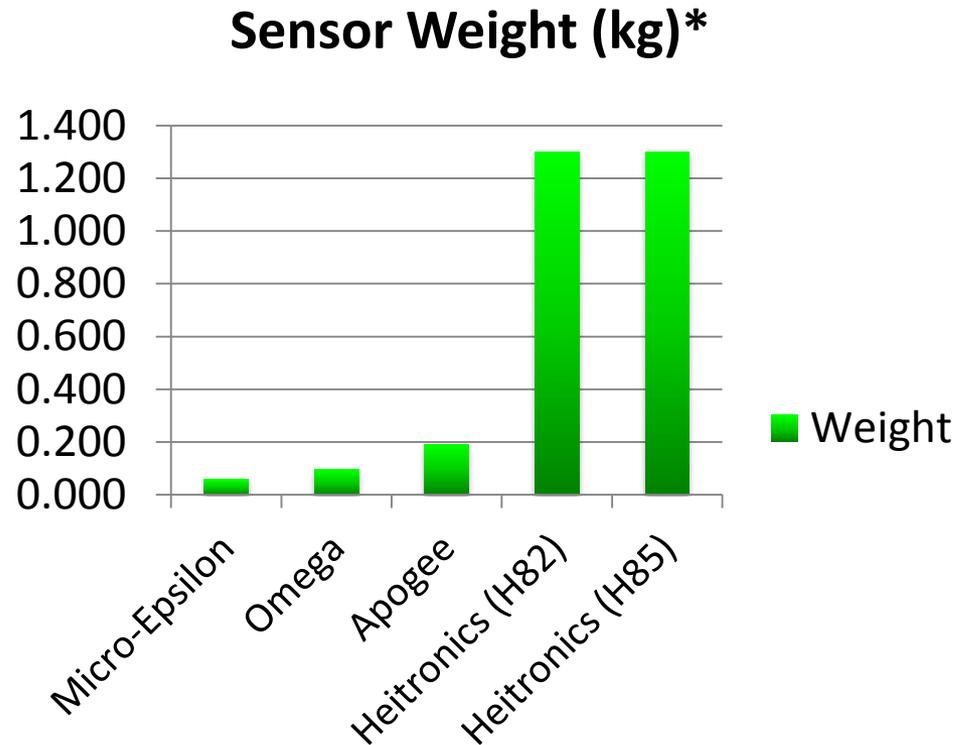
Rank	Sensor	Response Time
1	Micro-Epsilon "ThermoMETER CS"	0.03 s
2	Omega "OS301-LT"	0.24 s
3	Apogee "SI" Series	0.60 s
4a	Heitronics "KT15.82" (H82)	1.00
4b	Heitronics "KT15.85" (H85)	1.00



\*Lower values indicate improved performance attributes

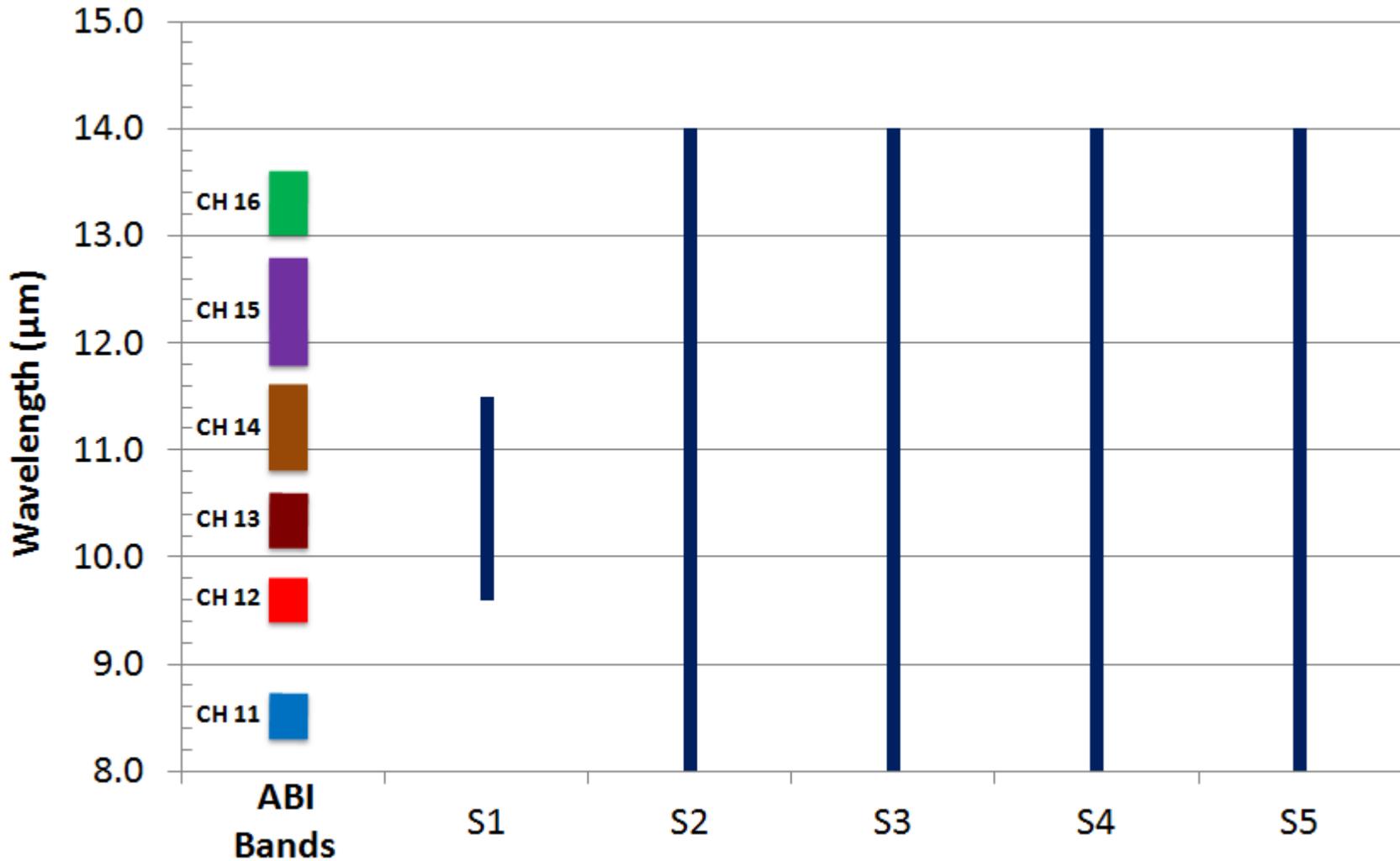
## Long-wave Spectral Sensors: Sensor Weight Comparison

Rank	Sensor	Sensor Weight
1	Micro-Epsilon "ThermoMETER CS"	0.058 kg
2	Omega "OS301-LT"	0.095 kg
3	Apogee "SI" Series	0.190 kg
4a	Heitronics "KT15.82" (H82)	1.300 kg
4b	Heitronics "KT15.85" (H85)	1.300 kg



\*Lower values indicate more desirable attributes

# Sensor Example Spectral Ranges and ABI Channels 11-16 Coverage



S1: Heitronics / KT15.85 IIP	S4: Micro-Epsilon / ThermoMETER CS
S2: Heitronics / KT15.82 IIP	S5: Omega / OS301-LT
S3: Apogee / "SI" Series	

# UV-VIS-NIR / 0.2-1.2 $\mu\text{m}$ Range Spectral Sensor Specifications

Manufacturer	Ocean Optics	StellarNet	Avantes
Sensor Model	"USB2000+"	"BLK-C-SR"	"AvaSpec-ULS2048XL"
Spectral Range ( $\mu\text{m}$ )	0.20 – 1.10	0.20 – 1.08	0.20 – 1.16
Dynamic Range	1,300:1 (for a single acquisition)	2,000:1 (w/ 6 decades)	3,800:1
Detector/ Type	Sony ILX511B/ CCD	Sony ILX511/ CCD (Toshiba TCD1201D PDA, optional)	Hamamatsu S11155-2048-01/ Back-thinned CCD
Pixel Count/ Size	2048 / 14x200 $\mu\text{m}$	2048 / 14x200 $\mu\text{m}$	2048 / 14x500 $\mu\text{m}$
Signal to Noise Ratio	250:1	CCD= 1,000:1 PDA= 2,000:1	450:1
Optical Resolution	1.5 nm	~ 1.5 nm	0.09 – 20 nm***
Integration Time	0.001 – 65 s	0.001 – 65 s	0.000002 – 20 s
Sensor Weight	0.190 kg*	~0.400 kg**	0.855 kg
Payload Dimensions (cm)	L x W x H: 8.9 x 6.3 x 3.4	L x W x H: 15.0 x 10.0 x 6.9	L x W x H: 17.5 x 11.0 x 4.4
Operational Environment Temperatures	-30 to 70 C	<i>(Not Provided)</i>	0 to 55 C
Operational Environment Humidity	0 to 90%, Non-condensing	<i>(Not Provided)</i>	10 to 90%, Non-condensing
Power	250 mA @ 5 VDC	100 mA @ 5 VDC	Default USB power, 450 mA ... or... With SPU2 external 12VDC, 200 mA

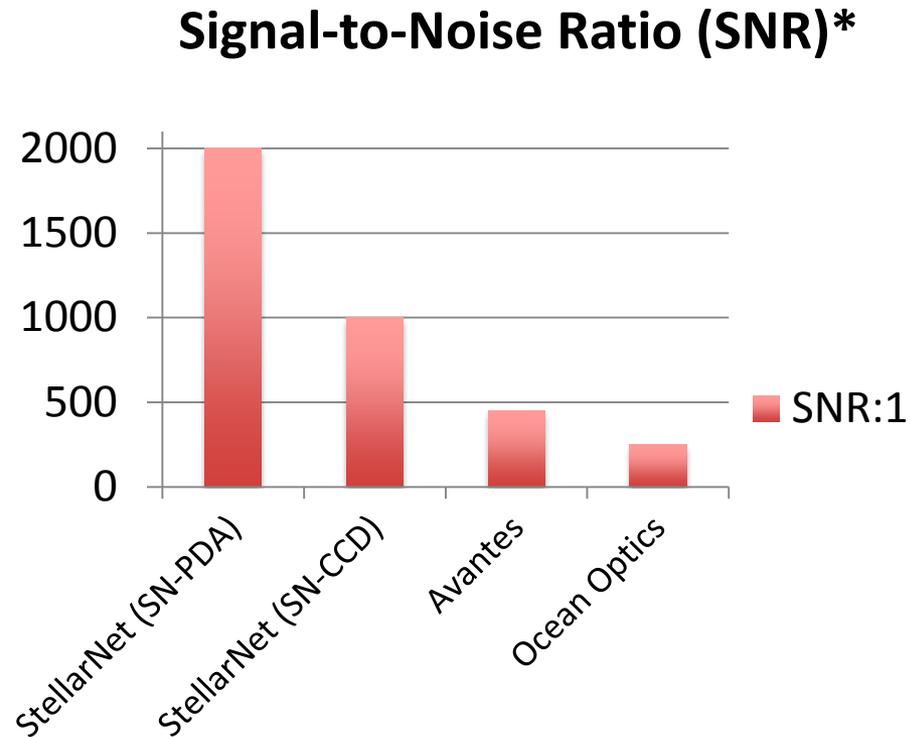
\* Includes full battery kit, Raspberry Pi processor, and cables

\*\* Estimated from similar sensors from this manufacturer with specs quoted at "14 ounces"

\*\*\* Resolution depends on grating configuration. Example: **1.5 nm** @ 25 $\mu\text{m}$  slit size w/ 300 lines/mm grating

# UV-VIS-NIR Spectral Sensors: Signal-to-Noise Ratio Comparison

Rank	Sensor	SNR
1	StellarNet "BLK-C-SR" (SN-PDA)**	2,000:1
2	StellarNet "BLK-C-SR" (SN-CCD)**	1,000:1
3	Avantes "AvaSpec-ULS2048XL"	450:1
4	Ocean Optics "USB2000+"	250:1



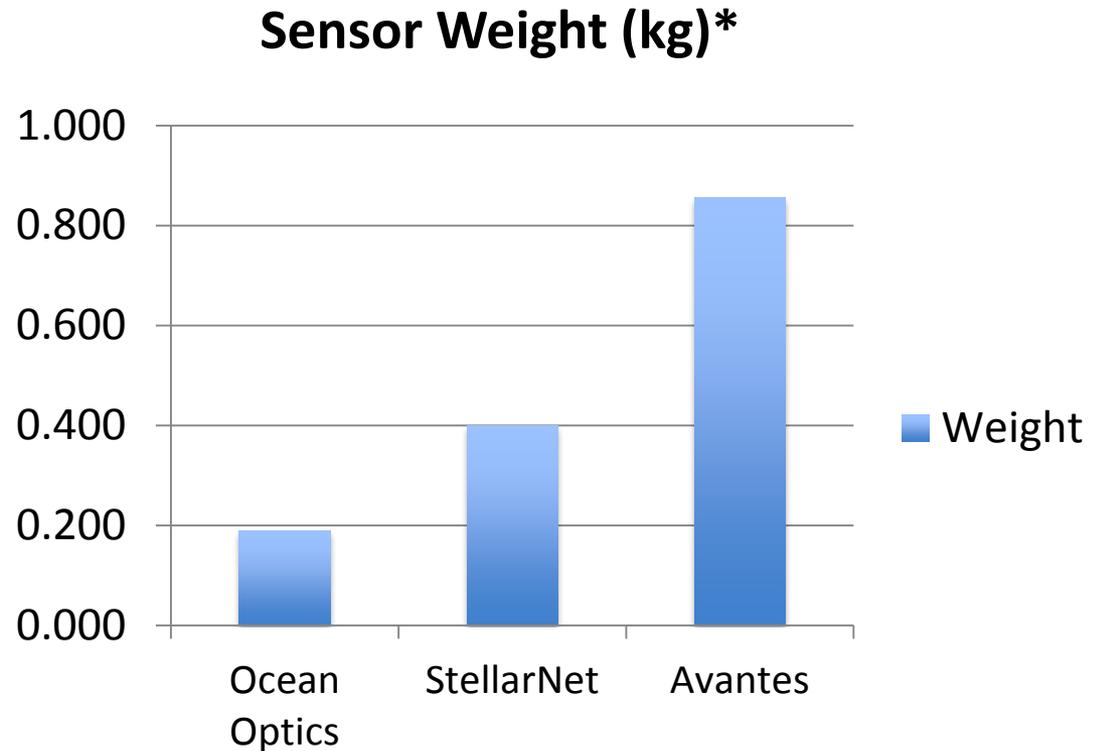
\*\* "Photodiode Array" (PDA)  
detector configuration

"Charge Coupled Device" (CCD)  
detector configuration

\*Higher ratios indicate improved performance attributes

## Long-wave Spectral Sensors: Sensor Weight Comparison

Rank	Sensor	Sensor Weight
1	Ocean Optics "USB2000+"	0.190 kg
2	StellarNet "BLK-C-SR"	0.400 kg
3	Avantes "AvaSpec-ULS2048XL"	0.855 kg



*\*Lower values indicate more desirable attributes*

# Near- to Short-wave IR (NIR/SWIR) / 0.9-2.6 $\mu\text{m}$ Range Spectral Sensor Specifications

Manufacturer	Ocean Optics	StellarNet	ARCOptix
<b>Sensor Model</b>	"NIRQuest512-2.5"	"RED-Wave-NIRX-SR"*	"FT-NIR Rocket"
<b>Spectral Range (<math>\mu\text{m}</math>)</b>	0.9 – 2.50 (w/ Grating NIR1)	0.90 – 2.30	0.9 – 2.60
<b>Dynamic Range</b>	7,500:1	4,000:1 (w/ 5 decades)	3,000:1
<b>Detector/ Type</b>	Hamamatsu G9208-512W InGaAs/ Linear PDA	Sensors Unlimited, Inc. LD InGaAs / Cooled Linear PDA	Extended type InGaAs/ Single Photodiode
<b>Pixel Count/ Size</b>	512 / 25x250 $\mu\text{m}$	512** / 25x250 $\mu\text{m}$	Single photodiode / <i>Not Provided</i>
<b>Signal to Noise Ratio</b>	10,000:1	400:1 (w/ 2x TEC cooling)	> 1,000:1 (single measurement) > 5,000:1 (25 avg measurements)
<b>Optical Resolution</b>	~6.3 nm	~26 nm**	0.8 nm @ 1.0 $\mu\text{m}$ 2.0 nm @ 1.7 $\mu\text{m}$ 5.0 nm @ 2.6 nm
<b>Integration Time</b>	0.001 – 0.20 s	0.001 – 0.25 s	<i>(Not Provided)</i>
<b>Sensor Weight</b>	1.18 kg (w/out power supply)	~0.400 kg***	0.850 kg
<b>Payload Dimensions (cm)</b>	L x W x H: 18.2 x 11.0 x 4.7	L x W x H: 15.0 x 10.0 x 6.9	L x W x H: 18.0 x 16.0 x 8.0
<b>Operational Environment Temperatures</b>	10 to 35 C	<i>(Not Provided)</i>	10 to 30 C
<b>Operational Environment Humidity</b>	0 to 90%, Non-condensing	<i>(Not Provided)</i>	<i>(Not Provided)</i>
<b>Power</b>	3,000 mA MAX @ 5 VDC	100 mA @ 5 VDC	5 V (USB Powered)

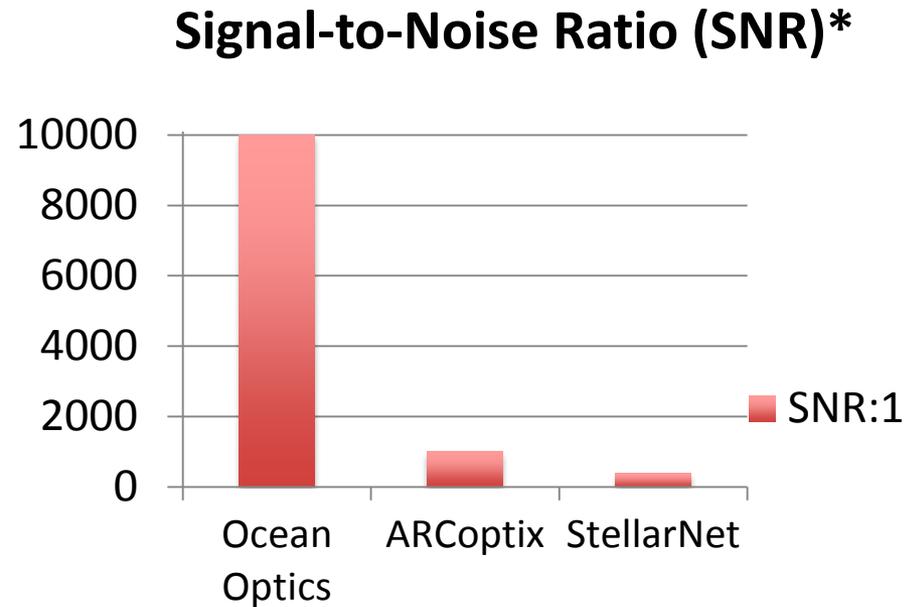
\* 'Can be coupled with StellarNet's BLACK-Comet (BLK-C) unit to cover the entire 0.20-2.30  $\mu\text{m}$  range.'

\*\* Optional detector configuration with 1024 pixel count; Yields increased optical resolution of ~14 nm

\*\*\* Estimated from similar sensors from this manufacturer with specs quoted at "14 ounces"

## NIR-SWIR Spectral Sensors: Signal-to-Noise Ratio Comparison

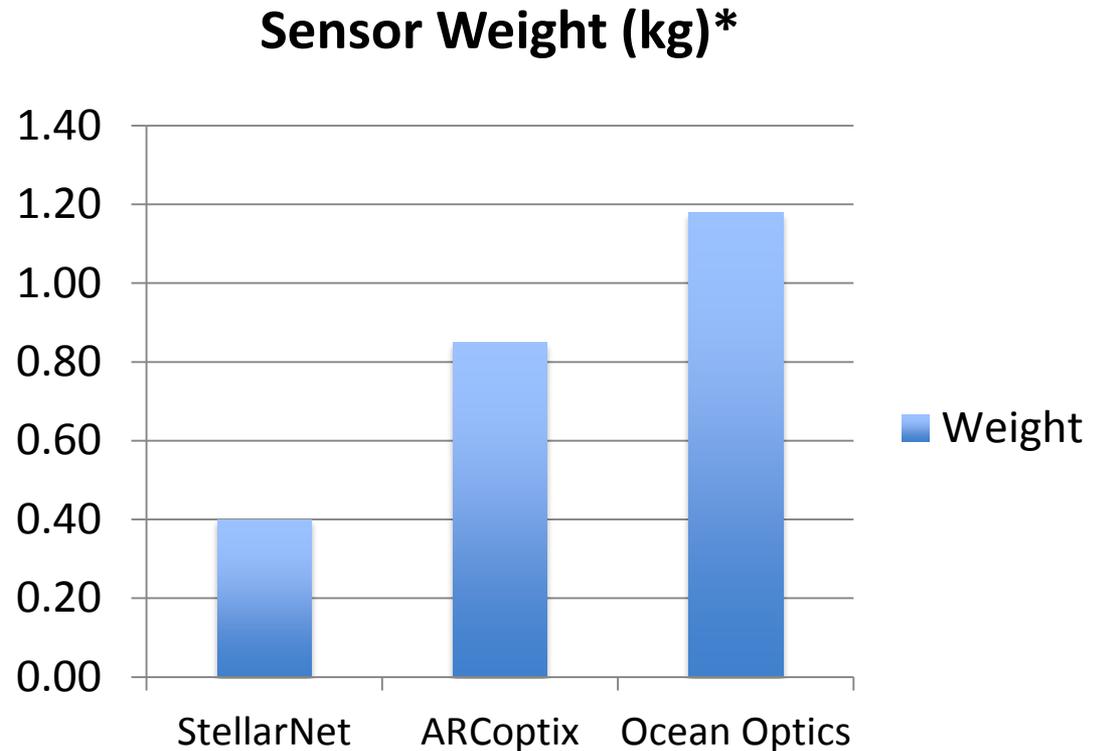
Rank	Sensor	SNR
1	Ocean Optics "NIRQuest512-2.5"	10,000:1
2	ARCOptix "FT-NIR Rocket"	1,000:1
3	StellarNet "RED-Wave-NIRX-SR"	400:1



*\*Higher ratios indicate improved performance attributes*

# NIR-SWIR Spectral Sensors: Sensor Weight Comparison

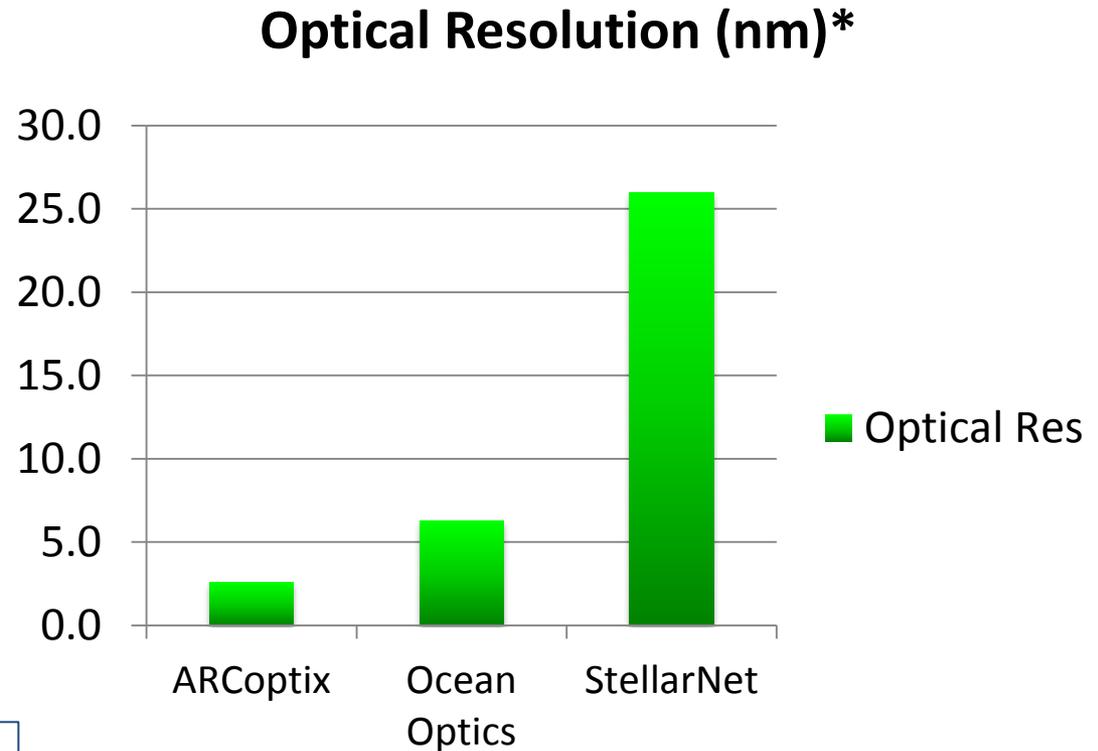
Rank	Sensor	Sensor Weight
1	StellarNet "RED-Wave-NIRX-SR"	0.40 kg
2	ARCOptix "FT-NIR Rocket"	0.85 kg
3	Ocean Optics "NIRQuest512-2.5"	1.18 kg



\*Lower values indicate more desirable attributes

# NIR-SWIR Spectral Sensors: Optical Resolution (aka: "Spectral Resolution") Comparison

Rank	Sensor	Optical/Spectral Resolution
1	ARCOptix "FT-NIR Rocket"	2.6 nm**
2	Ocean Optics "NIRQuest512-2.5"	6.3 nm
3	StellarNet "RED-Wave-NIRX-SR"	26.0 nm



**\*\* Averaged across spectrum with Extended Type InGaAs, single photodiode detector. Advertised specs for three spectral points:**

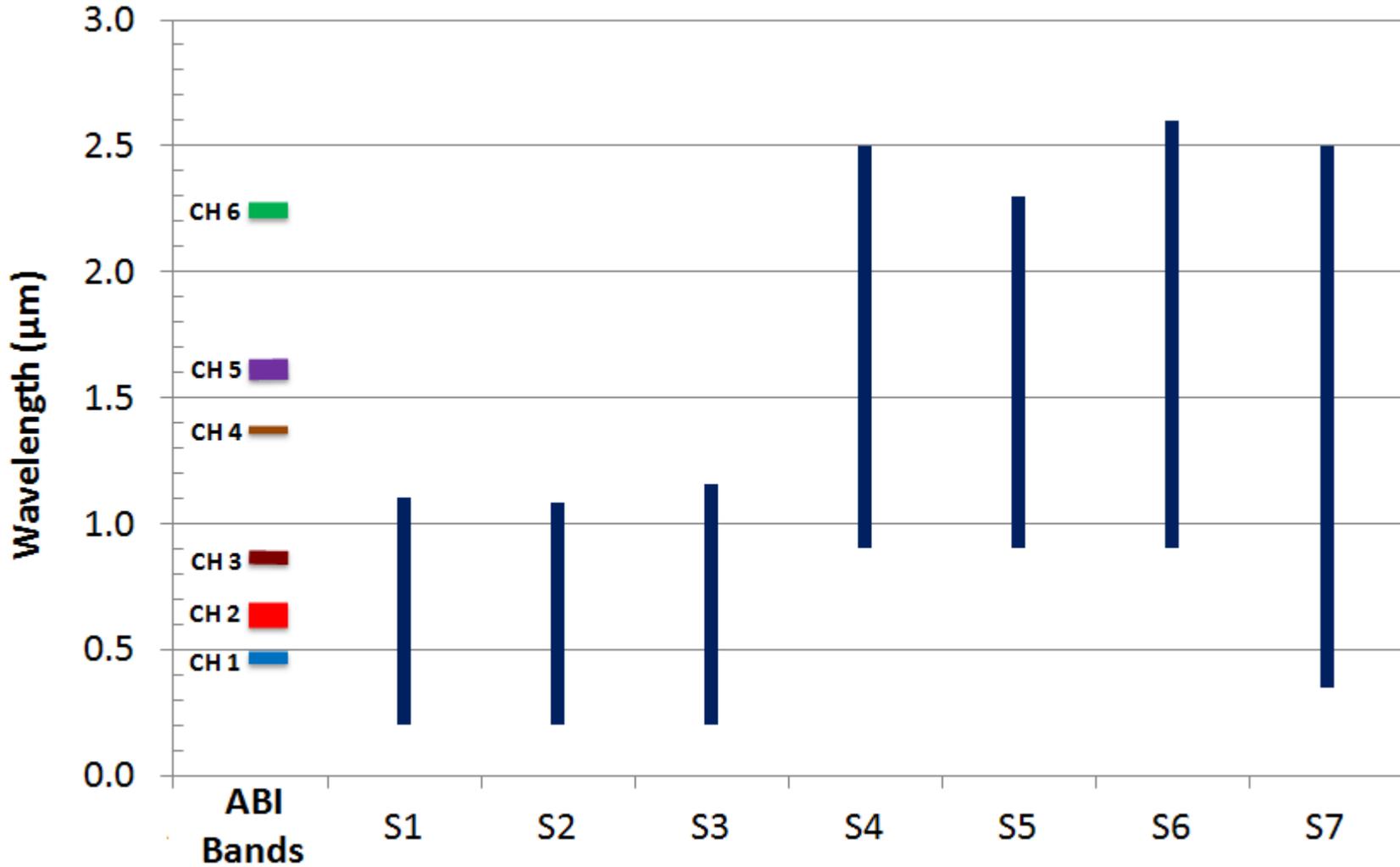
Opt Res= 0.8 nm @ 1.0um wavelength  
 Opt Res= 2.0 nm @ 1.7 um wavelength  
 Opt Res= 5.0 nm @ 2.6 nm wavelength

*\*Lower values indicate improved performance attributes*

# VIS to SWIR Integrated Option / 0.35-2.50 $\mu\text{m}$ Range Spectral Sensor Specifications

<b>Manufacturer</b>	<b>ASD Inc. (PANalytical)</b>
<b>Sensor Model</b>	“FieldSpec 4 Hi-Res”
<b>Spectral Range (<math>\mu\text{m}</math>)</b>	0.35 – 2.50
<b>Dynamic Range</b>	N/A for this type of sensor
<b>Detector/ Type</b>	VIS -VNIR (0.35-1.0 $\mu\text{m}$ ): 512 element silicon PDA SWIR 1 and SWIR2 (1.0-1.8 $\mu\text{m}$ and 1.8-2.5 $\mu\text{m}$ ): Graded Index InGaAs PDA, TE Cooled (single diode)
<b>Pixel Count/ Size</b>	VNIR: 512 / 50x2,500 $\mu\text{m}$ SWIR1 and SWIR2: Single photodiode, each / 1,000x1,000 $\mu\text{m}$
<b>Signal to Noise Ratio</b>	SNR is N/A for this type of sensor. However, the Noise Equivalent Delta Radiance (NEDL) is as follows: VNIR 1.0 X10 <sup>-9</sup> W/cm <sup>2</sup> /nm/sr @ 700 nm SWIR 1 1.4 X10 <sup>-9</sup> W/cm <sup>2</sup> /nm/sr @ 1400 nm SWIR 2 2.2 X10 <sup>-9</sup> W/cm <sup>2</sup> /nm/sr @ 2100 nm
<b>Optical Resolution</b>	3 nm @ VIS 8 nm @ SWIR
<b>Integration Time</b>	For VNIR: 0.009 – 0.136 s
<b>Sensor Weight</b>	5.44 kg
<b>Payload Dimensions (cm)</b>	L x W x H: 36.8 x 29.2 x 12.7
<b>Operational Environment Temperatures</b>	0 to 40 C
<b>Operational Environment Humidity</b>	0 to 100%, Non-condensing
<b>Power</b>	12 VDC / 60 Watts

# Sensor Example Spectral Ranges and ABI Channels 1-6 Coverage



S1: Ocean Optics / USB2000+	S4: Ocean Optics / NIRQuest512-2.5	S7: ASD Inc. / FieldSpec 4 Hi-Res
S2: StellarNet / BLK-C-SR	S5: StellarNet / RED-Wave-NIRX-SR	
S3: Avantes / AvaSpec-ULS2048XL	S6: ARCOptix / FT-NIR Rocket	



# NOAA GOES-R Advanced Baseline Imager Calibration and Validation UAS Mission Overview



## **Proposed CONOPS Review: Oceanic Cal/Val Component**

### ▶ **Definition: Single Pass from One Target Collection**

- Maintain a fixed radius of 10 meters, ideally (no more than 15 meters)
- Start at a large off-nadir angle (70 to 90 degrees), then fly VTOL UAS on an arc up and over a fixed ocean target, ending the pass at the same off-nadir angle on the other side
- Sensors remain fixed on the target during the entire overpass.

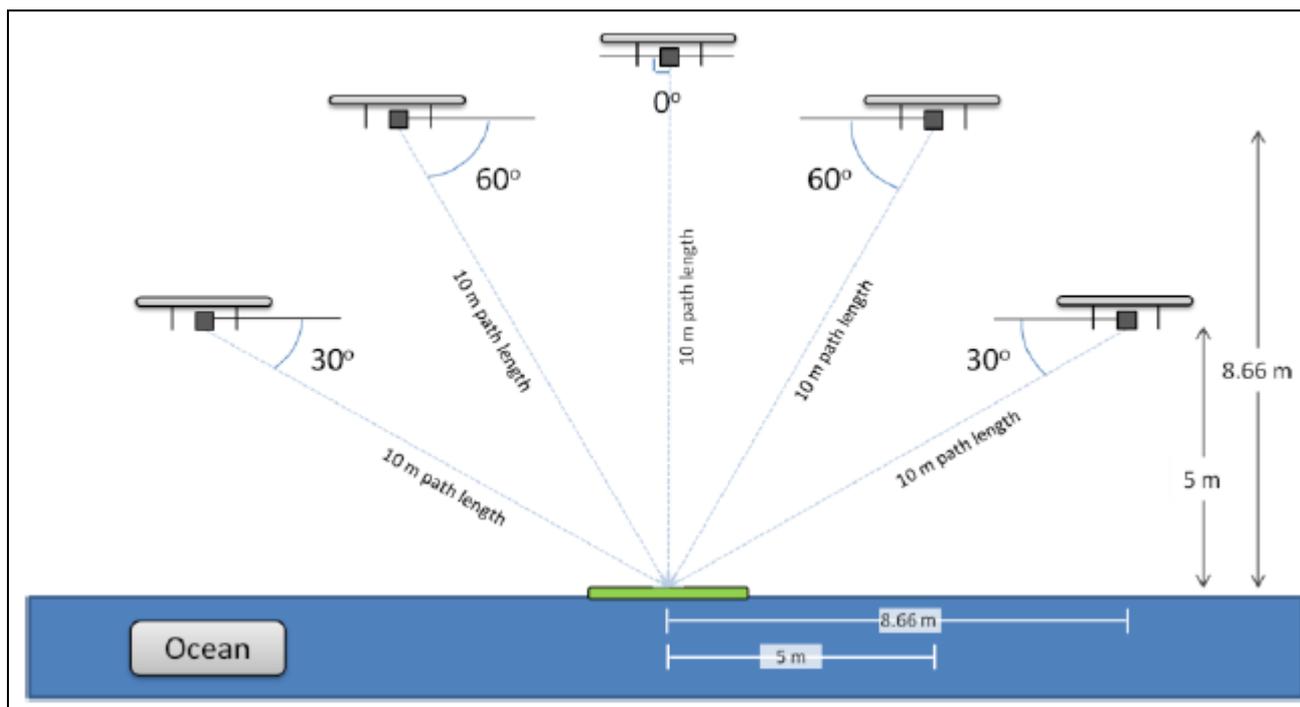
### ▶ **Definition: Complete Collection for One Target**

- Repeat for a total of four passes, rotating azimuthally around a target, essentially piecing together a collection of target observations from as many different observation angles within the skyward hemisphere as possible.

### ▶ **Definition: Full Mission Collection**

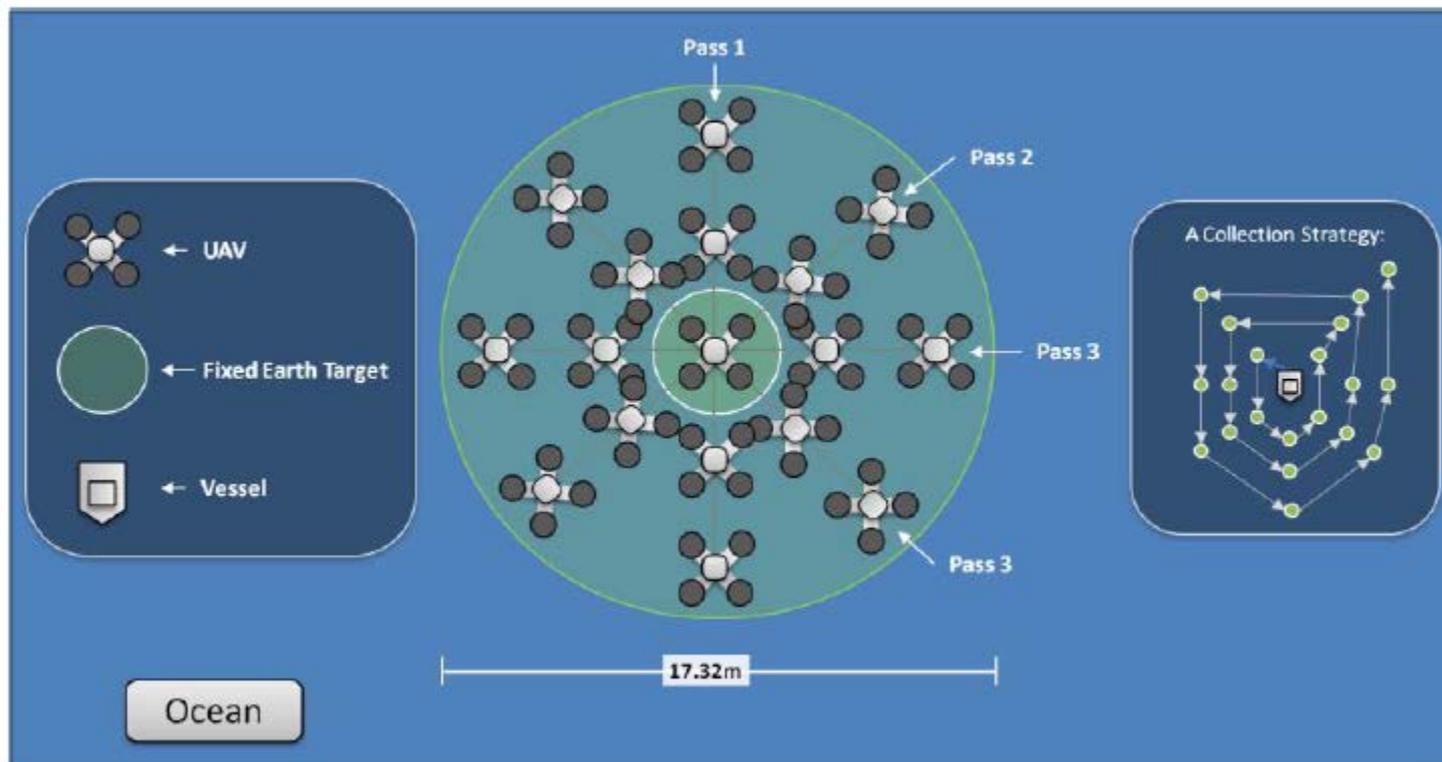
- Repeat target observation collections for multiple targets, radiating outward from a central location (likely a ship) until a sizeable enough footprint of the ocean surface has been sampled (initially proposed to be ~1 to 5 km out in all directions.)

## Proposed CONOPS Review: Oceanic Cal/Val Component



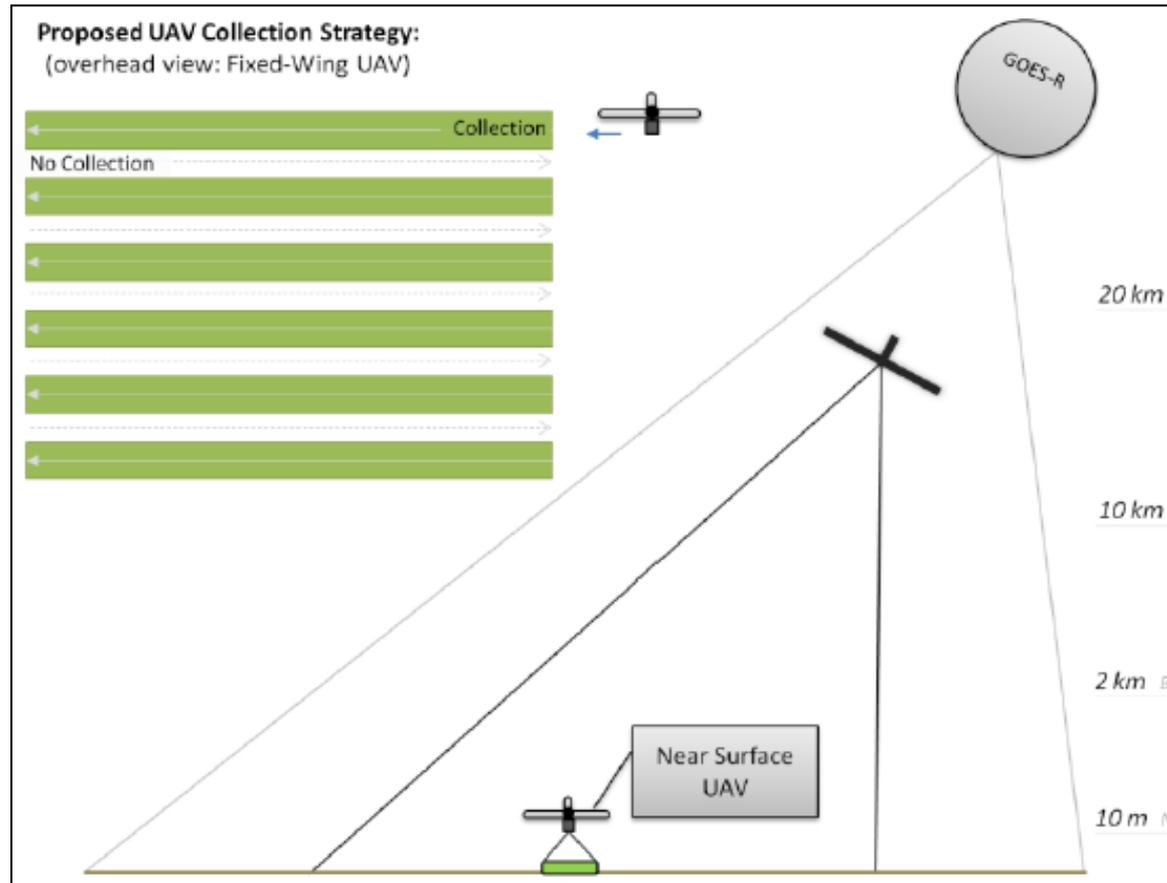
**Figure 1:** Schematic of proposed goniometric measurements, illustrating a single pass-over of a fixed ocean target by a VTOL UAS platform  
(Provided from original GOES-R Cal/Val team UAS requirements draft)

## Proposed CONOPS Review: Oceanic Cal/Val Component



**Figure 2:** Schematic of a complete observation collection as proposed for a single target. A full collection consists of four single passes over the target... see Figure 1. (Provided from original GOES-R Cal/Val team UAS requirements draft)

## Proposed CONOPS Review: Land Cal/Val Component



**Figure 3:** Schematic of the fixed wing UAS observation collection strategy. The GOES-R Cal/Val team has noted that the collection does not require continuous coverage.

(Provided from original GOES-R Cal/Val team UAS requirements draft)



# Observing Strategies by Fixed Wing UAS Capabilities and Science Focus Area



UAS Platform	High Impact Weather	Marine	Polar
<b>HALE</b> 	<b>RESEARCH</b> Oceanic storm vertical meteorological profiles Ocean storm surface winds / rain High altitude air quality		<b>DEVELOPMENT</b> Arctic weather vertical meteorological profiles Arctic high altitude air quality  <b>RESEARCH</b> Sea Ice surveys
<b>MALE</b> 	<b>DEMONSTRATION</b> Flood aerial surveys  <b>RESEARCH</b> Continental storm damage assessment -	<b>DEMONSTRATION</b> Maritime enforcement surveys Wildlife surveys  <b>RESEARCH</b> Coastal gravity observations	<b>RESEARCH</b> Flood aerial surveys
<b>LALE</b> 	<b>RESEARCH</b> Continental storm in situ observations Continental storm damage assessment	<b>RESEARCH</b> Wildlife assessments	<b>DEMONSTRATION</b> Sea ice surveys Arctic weather in situ observations Arctic in situ air quality  <b>DEVELOPMENT</b> Arctic icing weather observations Wildlife assessments
<b>LASE</b> 	<b>DEMONSTRATION</b> Flood aerial surveys  <b>DEVELOPMENT</b> Flood digital elevation mapping Continental storm in situ observations  <b>RESEARCH</b> Continental storm damage assessment	<b>DEMONSTRATION</b> Maritime enforcement surveys Maritime oil spill aerial surveys Maritime oil spill response imagery Marine debris response imagery Wildlife aerial surveys  <b>RESEARCH</b> Coastal digital elevation mapping	<b>DEMONSTRATION</b> Sea ice aerial surveys for ships Arctic oil spill aerial surveys



# Observing Strategies by Other Unmanned Capabilities and Science Focus Area



UAS Platform	High Impact Weather	Marine	Polar
<b>VTOL</b> 	<b>RESEARCH</b> Continental storms in situ meteorological observations Air quality in situ observations	<b>DEMONSTRATION</b> Maritime oil spill response imagery Wildlife assessments	<b>DEMONSTRATION</b> Wildlife assessments
<b>ACL</b> 	<b>DEMONSTRATION</b> Oceanic storm low altitude in situ meteorological observations		
<b>BL</b> 	<b>DEMONSTRATION</b> Air quality vertical profiles		<b>RESEARCH</b> Arctic air quality vertical profiles
<b>SMUV</b> 	<b>DEVELOPMENT</b> Oceanic storm low altitude in situ meteorological observations	<b>DEVELOPMENT</b> Maritime assessments Wildlife assessments Coastal assessments	
<b>TB</b> 		<b>RESEARCH</b> Maritime assessments	<b>RESEARCH</b> Arctic maritime assessments